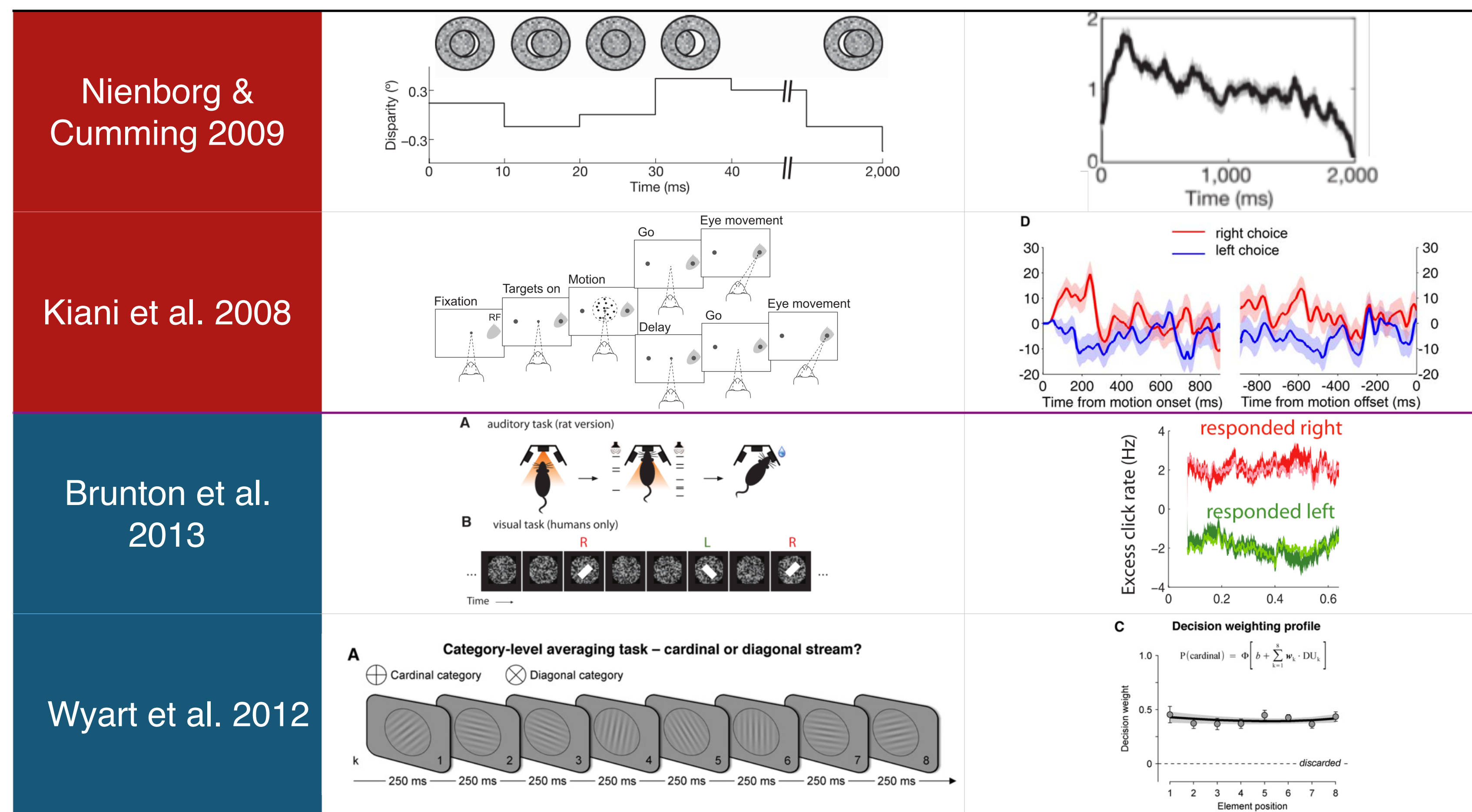


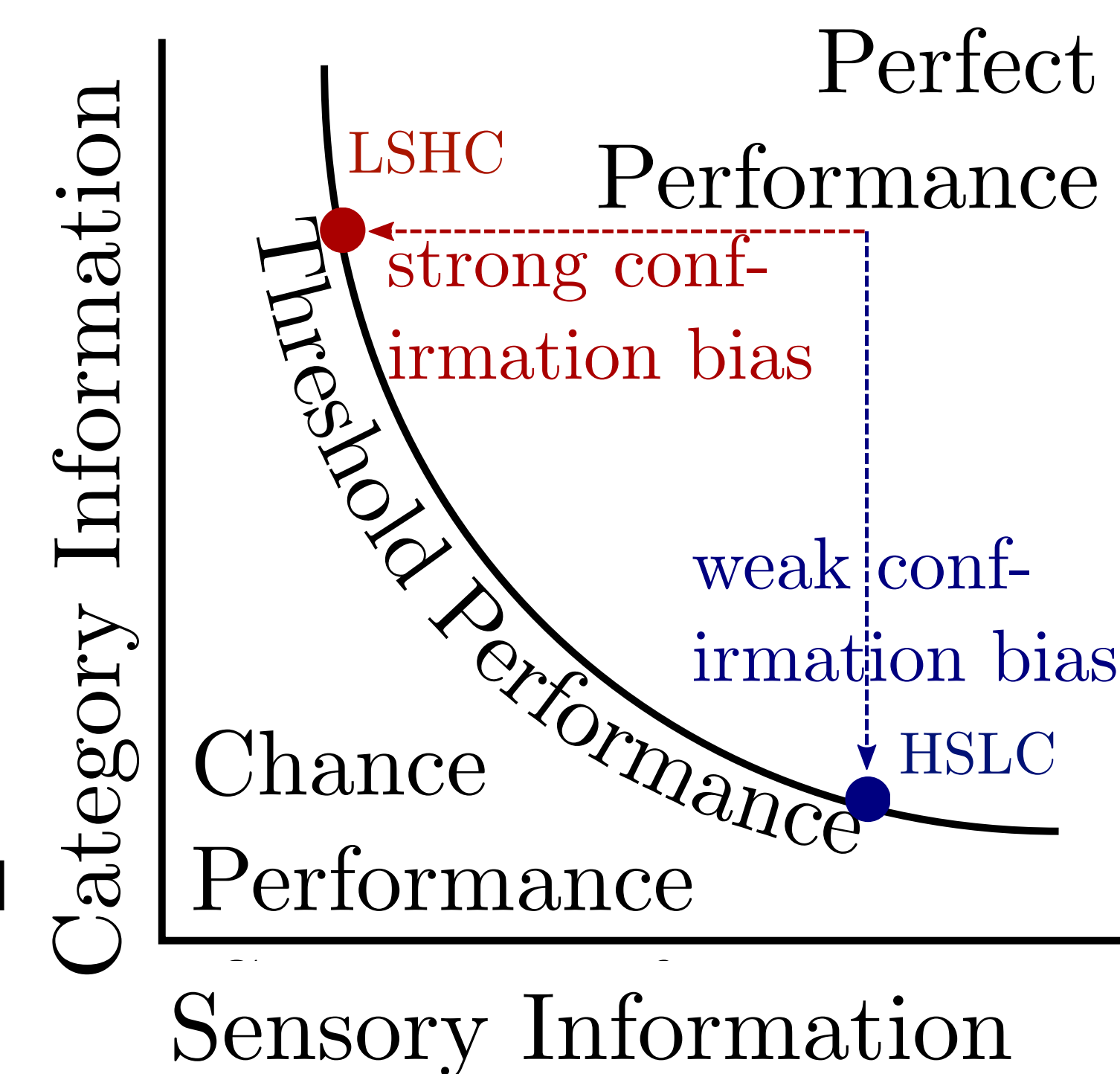
Introduction

In **evidence integration** tasks, subjects make a categorical decision from a sequence of (typically i.i.d.) sensory information.
 A **psychophysical kernel (PK)** quantifies the 'weight' subjects give to evidence in space or in time.
 A **confirmation bias (CB)** occurs when people upweight information confirming existing beliefs, thus strengthening those beliefs.
 A **Perceptual CB** implies a PK that decreases over time.
 Different studies have reported different temporal PK shapes, typically flat or decreasing.



Our Framework

2 Sources of uncertainty:
 With **high-contrast stimuli** that are each **weakly predictive** of the correct choice, recency (or flat weights) observed
 With **low-contrast stimuli** that are each **highly predictive** of the correct choice, primacy is observed.
Threshold performance is achieved at a balance between these.



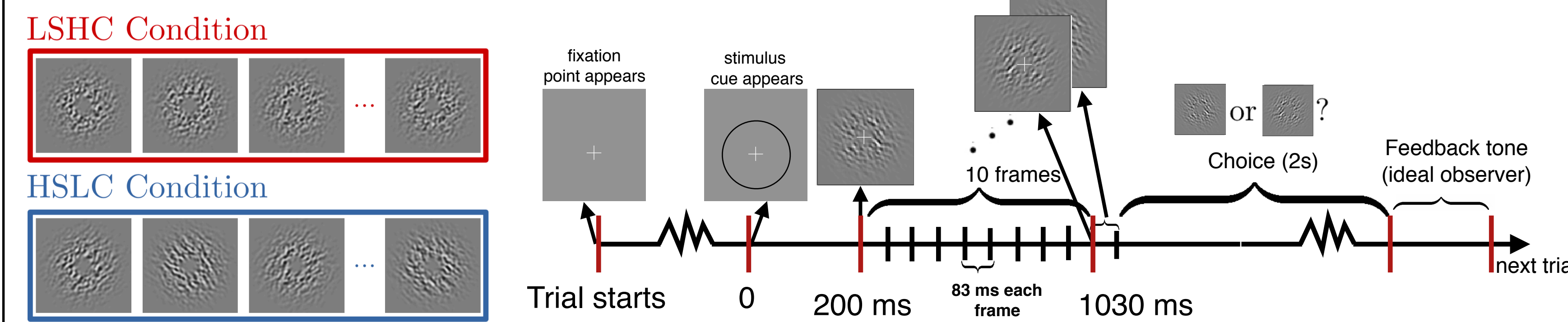
Category information: probability of an ideal observer guessing the category of a single 'frame' \mathbf{x}_t given \mathbf{C}
 We define **sensory** or **likelihood information** as the probability of guessing \mathbf{x}_t given \mathbf{e}_t

Experiments

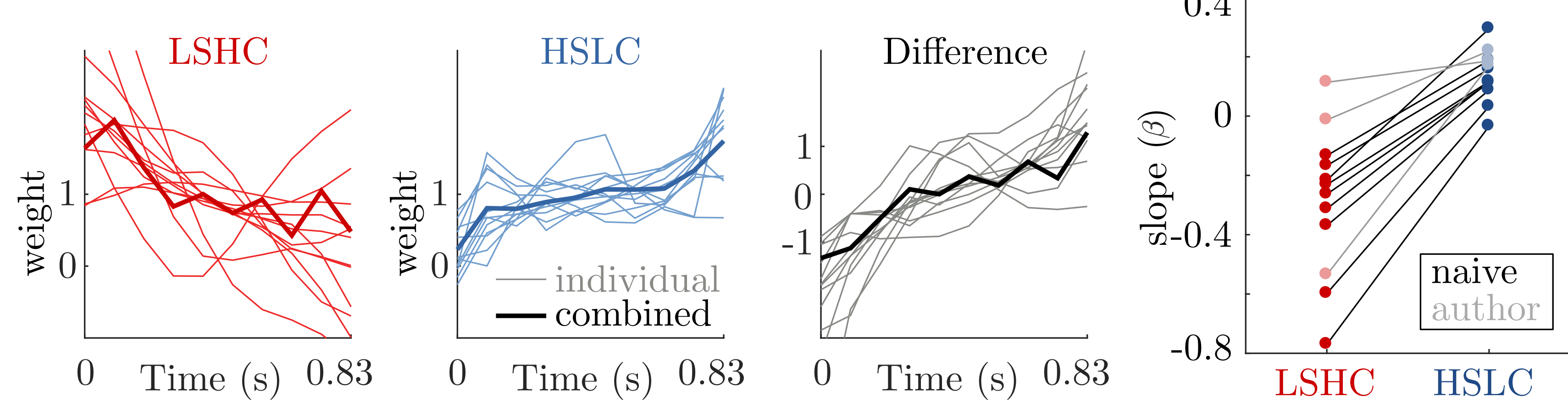
We used an orientation-discrimination paradigm with orientation-band-pass stimuli.

- In the **LSHC context** staircase on the **noise** is run to reach 70% performance
- In the **HSLC context**, a staircase is run on **p_{prior}**
- Both tasks' staircases begin at the same set of parameters.

Task Design



Behavioral Results



Change in PK slopes consistent with our framework's predictions, but significant variability between subjects (possibly explained by different γ ?).

Sampling Model^[5,6]

Generative model:
 \mathbf{C} = category / decision-area
 \mathbf{x} = sensory representation
 \mathbf{e} = evidence

Goal: compute posterior over \mathbf{C} given \mathbf{e}

$$p(\mathbf{C} | \mathbf{e}_1, \dots, \mathbf{e}_T) \propto p(\mathbf{C}) \prod_{t=1}^T p(\mathbf{e}_t | \mathbf{C})$$

...using **online updates**

$$\log \frac{p_t(\mathbf{C} = +1)}{p_t(\mathbf{C} = -1)} \equiv \log \frac{p(\mathbf{C} = +1 | \mathbf{e}_1, \dots, \mathbf{e}_t)}{p(\mathbf{C} = -1 | \mathbf{e}_1, \dots, \mathbf{e}_t)}$$

$$= \log \frac{p_{t-1}(\mathbf{C} = +1)}{p_{t-1}(\mathbf{C} = -1)} + \log \frac{p(\mathbf{e}_t | \mathbf{C} = +1)}{p(\mathbf{e}_t | \mathbf{C} = -1)}$$

update to log posterior odds each frame

...using **importance sampling** from the **full posterior** to marginalize over the sensory variable \mathbf{x}

$$p(\mathbf{e}_t | \mathbf{C} = c) = \int p(\mathbf{e}_t | \mathbf{x}_t) p(\mathbf{x}_t | \mathbf{C} = c) \approx \frac{1}{S} \sum_{\mathbf{x}^{(i)} \sim Q} p(\mathbf{e}_t | \mathbf{x}_t^{(i)}) p(\mathbf{x}_t^{(i)} | \mathbf{C} = c) / Q(\mathbf{x}_t^{(i)})$$

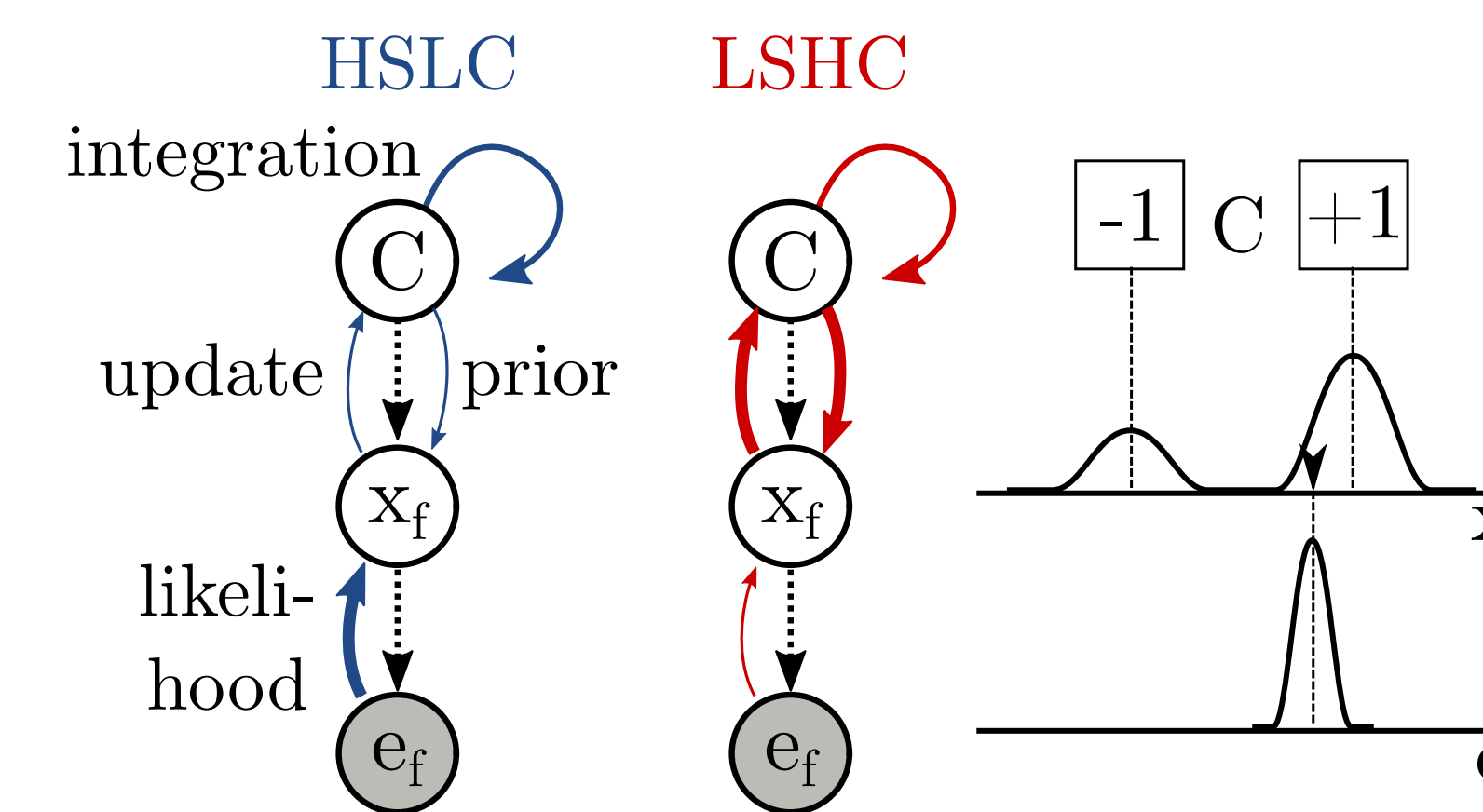
$$\log \frac{p(\mathbf{e}_t | \mathbf{C} = +1)}{p(\mathbf{e}_t | \mathbf{C} = -1)} \approx \log \frac{\sum p(\mathbf{x}_t^{(i)} | \mathbf{C} = +1) w_i}{\sum p(\mathbf{x}_t^{(i)} | \mathbf{C} = -1) w_i}$$

$$w_i = \left(\sum_c p(\mathbf{x}_t^{(i)} | \mathbf{C} = c) p_{t-1}(\mathbf{C} = c) \right)^{-1}$$

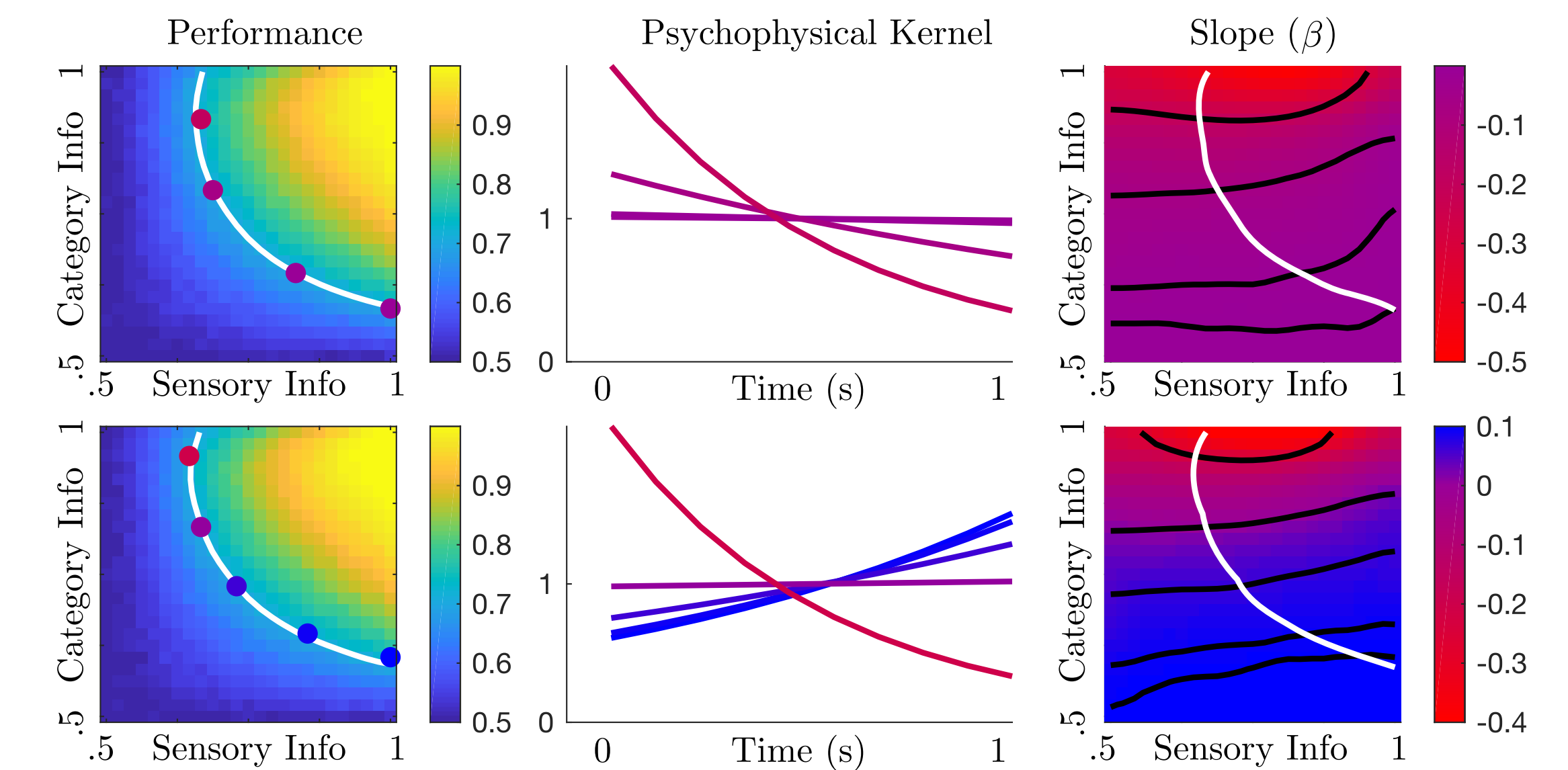
Final update rule:

$$\log \frac{p_t(\mathbf{C} = +1)}{p_t(\mathbf{C} = -1)} \approx \log \frac{p_{t-1}(\mathbf{C} = +1)}{p_{t-1}(\mathbf{C} = -1)} + \log \frac{\sum_{i=1}^S p(\mathbf{x}_t^{(i)} | \mathbf{C} = +1) w_i}{\sum_{i=1}^S p(\mathbf{x}_t^{(i)} | \mathbf{C} = -1) w_i} - \gamma \log \frac{p_{t-1}(\mathbf{C} = +1)}{p_{t-1}(\mathbf{C} = -1)}$$

bias correction (small S)



Sampling Model
 $\gamma = 0$



Sampling Model
 $\gamma = 0.1$

Variational (Parametric) Model^[7,8]

Same setup and objective as sampling model, except approximation is due to **mean field assumption**:

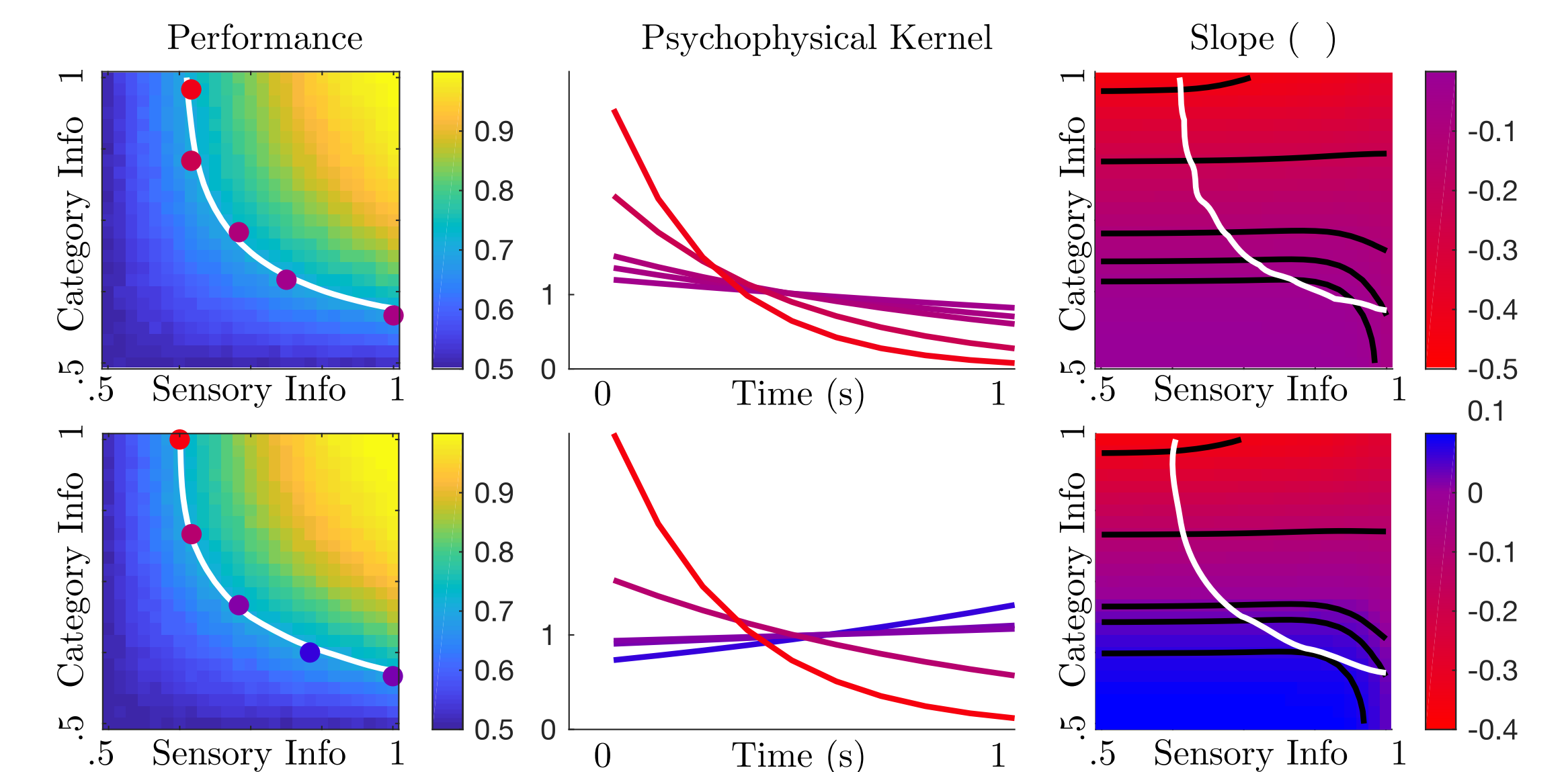
$$p(\mathbf{C}, \mathbf{x} | \mathbf{e}) \approx q(\mathbf{C}) q(\mathbf{x})$$

Inference is done using Mean Field Variational Bayes, which passes messages between $q(\mathbf{C})$ and $q(\mathbf{x})$ to approach a minimum of $\text{KL}(q||p)$. Here, the updates (with an auxiliary variable \mathbf{z}) are:

$$\log q(\mathbf{C}) = \log p(\mathbf{C}) + \mu_z \mu_x / \sigma_x^2 \quad \log q(\mathbf{z}) = \log p(\mathbf{z}) + \mu_C \mu_x / \sigma_x^2$$

$$q(\mathbf{x}) = \mathcal{N} \left(\mathbf{x}; \frac{\sigma_e^2 \mu_C + \sigma_x^2 \mu_z e}{\sigma_x^2 + \sigma_e^2}, \frac{\sigma_x^2 \sigma_e^2}{\sigma_x^2 + \sigma_e^2} \right)$$

Variational Model
 $\gamma = 0$



Variational Model
 $\gamma = 0.1$

Conclusions

Feedback of priors is required for sensory areas to represent full posteriors, but potentially at the cost of biased evidence accumulation due to "double counting" the prior.
 This **perceptual confirmation bias** effect explains discrepancy in past studies as well as within-subject differences in the present study.

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